



# Six years of mobile milking at experimental farm Trévarez in France

**Valérie BROCARD, Institut de l'Élevage, France**

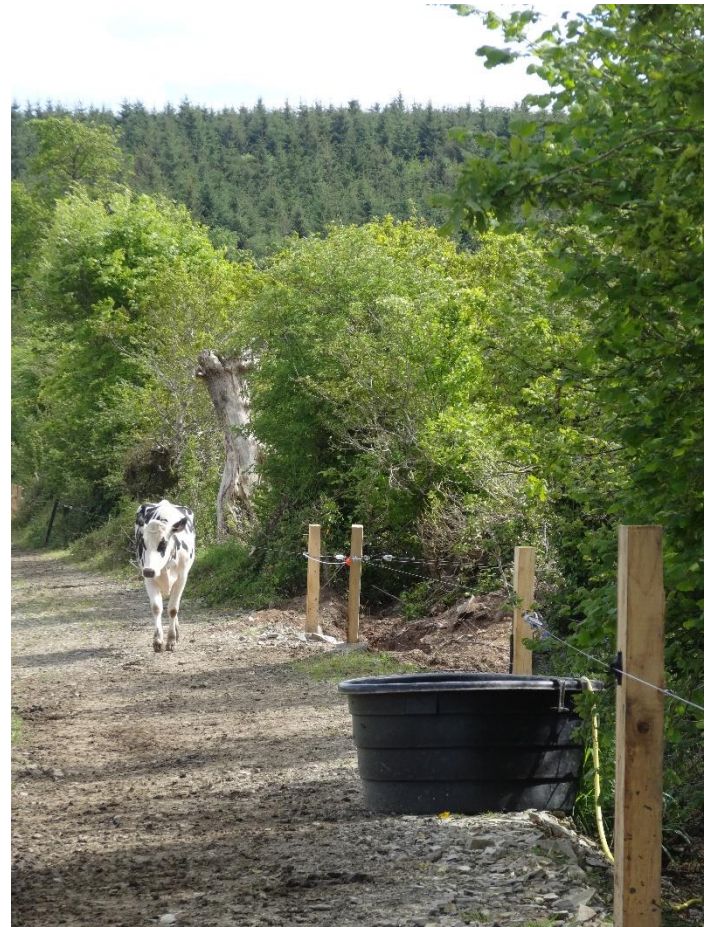
**[valerie.brocard@idele.fr](mailto:valerie.brocard@idele.fr)**

**Estelle CLOET, Chambres d'agriculture de Bretagne,  
France**

**[estelle.cloet@bretagne.chambagri.fr](mailto:estelle.cloet@bretagne.chambagri.fr)**

# Combining Robotic Milking and Grazing

- in a 100% grazed grass system in organic production  
(Trevarez experimental Farm, Brittany)



# The base of the farm production system

Certified organic since May'15

- 85 ha
- 55 Holstein cows
- Production: 5,200 kg cow<sup>-1</sup> yr<sup>-1</sup>
- Crossbreeding in progress
- 2 \* 3 months calving periods (spring and autumn)

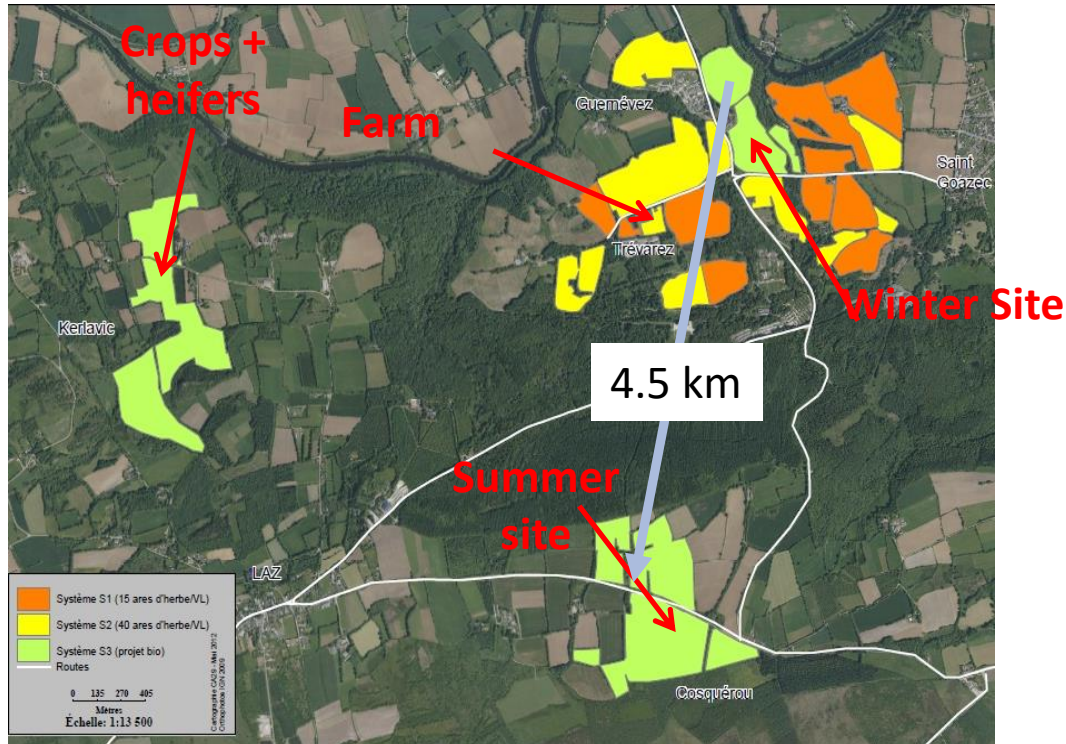


Target: maximal feeding and protein self sufficiency  
(no purchase of concentrate)

- Maximal grass use, minimal concentrate use
- Minimal working time (no fetching of cows)



# The background: a fragmented land design for a grass based system



The robot trailer inside the winter shed



The tank trailer

# The solution: a mobile robot

The summer  
location  
(6 months per  
year)





# The robot on the summer site

Camera

Concentrate silo

Robot trailer

Tank trailer

Trévarez



3 directions drafting gate

Stabilized track

Waiting area/ slatted floor / pit

# The transfer management: not a problem

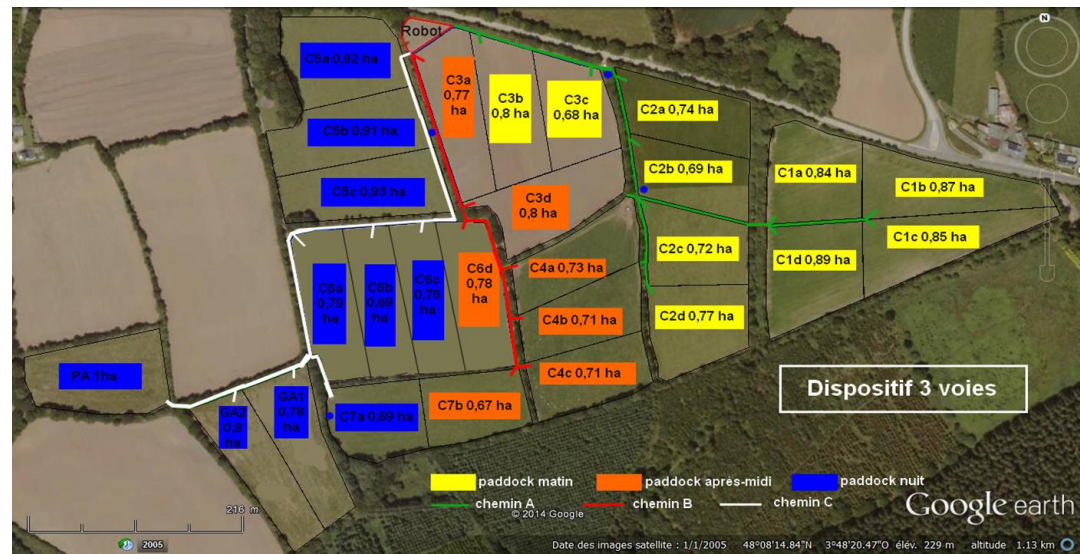
Number of transfers (*2) performed until now	6
Distance winter site- summer site	4.5 km
Time required (human hours)	13-17 h (3 to 4 people)
Transfer of	Cows, tank, robot, drafting gate
Robot stopped	3-4 h

- Does not require presence of AMS retailer
- Duration of transfer = silage organisation

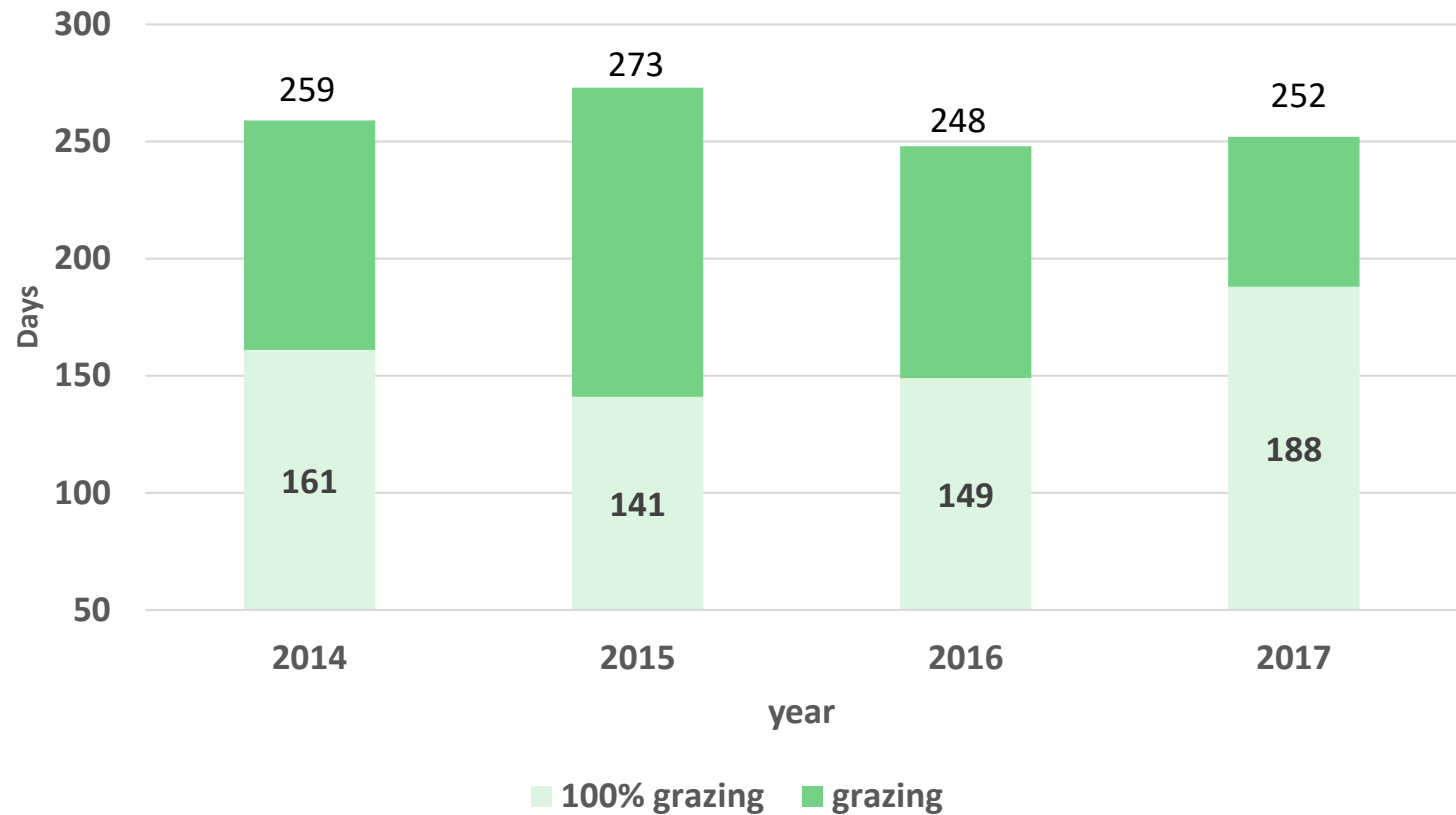
# Grass management: the motivation factor for cow flow

Access to new  
paddock after robot

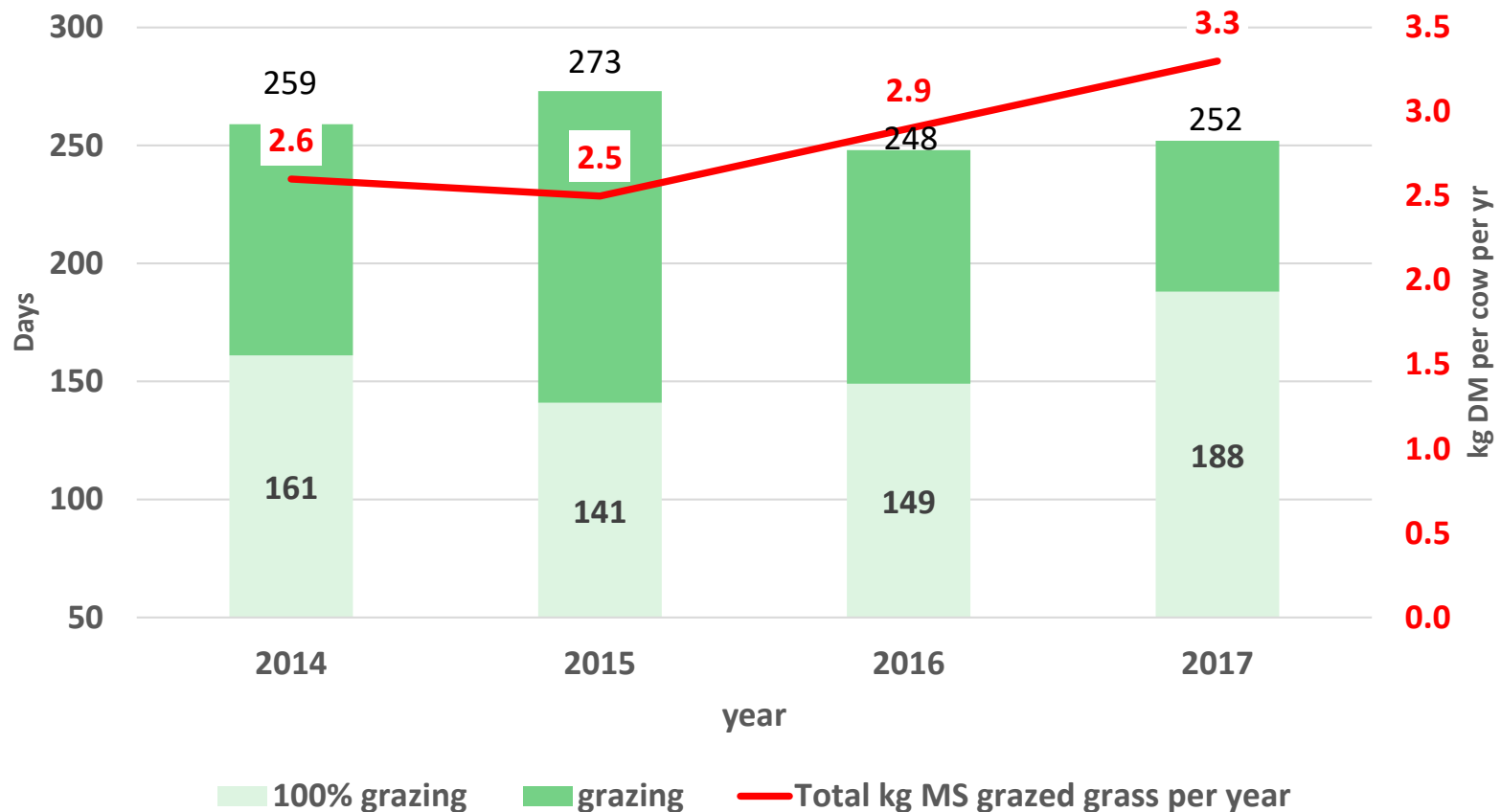
- Rotational grazing with front fence  
Paddocks of 0,7 to 1 ha
- Main tracks stabilized
- Waterpoints located on the tracks
- Grass cover and growth assessed by weekly platometer measurements
- AB or ABC system (experiments), monitoring with drafting gate.
- <1 kg concentrate per cow per day
- No buffer feed







- 250 days grazing, 5 to 6 months 100% grazing



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- Grazed grass intake increased up to 3.3 t DM per cow per yr

# Daily performances on the summer site

YEAR	2014	2015	2016	2017
<b>Grazing system</b>	<b>AB</b>	<b>ABC</b>	<b>ABC</b>	<b>AB</b>
# milking cows	46	52	52	46
Milk per box (kg per d )	867	911	914	786
<b>Production per cow per day (kg)</b>	<b>18.6</b>	<b>17.6</b>	<b>17.7</b>	<b>17.1</b>
Milking frequency (per cow per day)	1.8	1.8	1.7	1.5
<b>Concentrate (kg per cow per day)</b>	<b>0.9</b>	<b>0.7</b>	<b>0.7</b>	<b>0.7</b>

0.7 kg  
conc

18 kg  
milk

1.6  
milkings



# Conclusion:

## Mobility = Technically realistic

- Mobile robot robust, no technical issue until now
- Transfers = not a problem
- Grass use = 4 times higher than regional average for AMS farms
- Herd performances satisfactory for organic system
- Key factor for success: a well stabilized waiting area

# Summer site versus winter site

Feeding cost = -75 %

Working time =  
-2 h per day

What else?

Animal welfare  
Health  
Image  
Environment

# Thank you for your attention



[estelle.cloet@bretagne.chambagri.fr](mailto:estelle.cloet@bretagne.chambagri.fr)

[valerie.brocard@idele.fr](mailto:valerie.brocard@idele.fr)