



# Six years of mobile milking at experimental farm Trévarez in France

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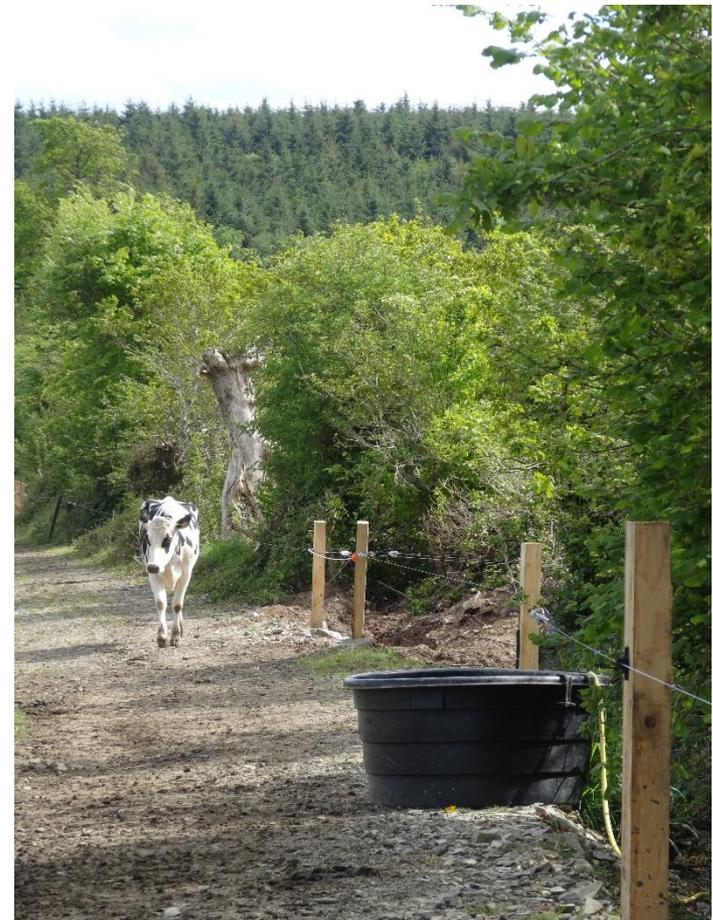
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# Combining Robotic Milking and Grazing

- in a 100% grazed grass system in organic production  
(Trevarez experimental Farm, Brittany)



# The base of the farm production system

Certified organic since May'15

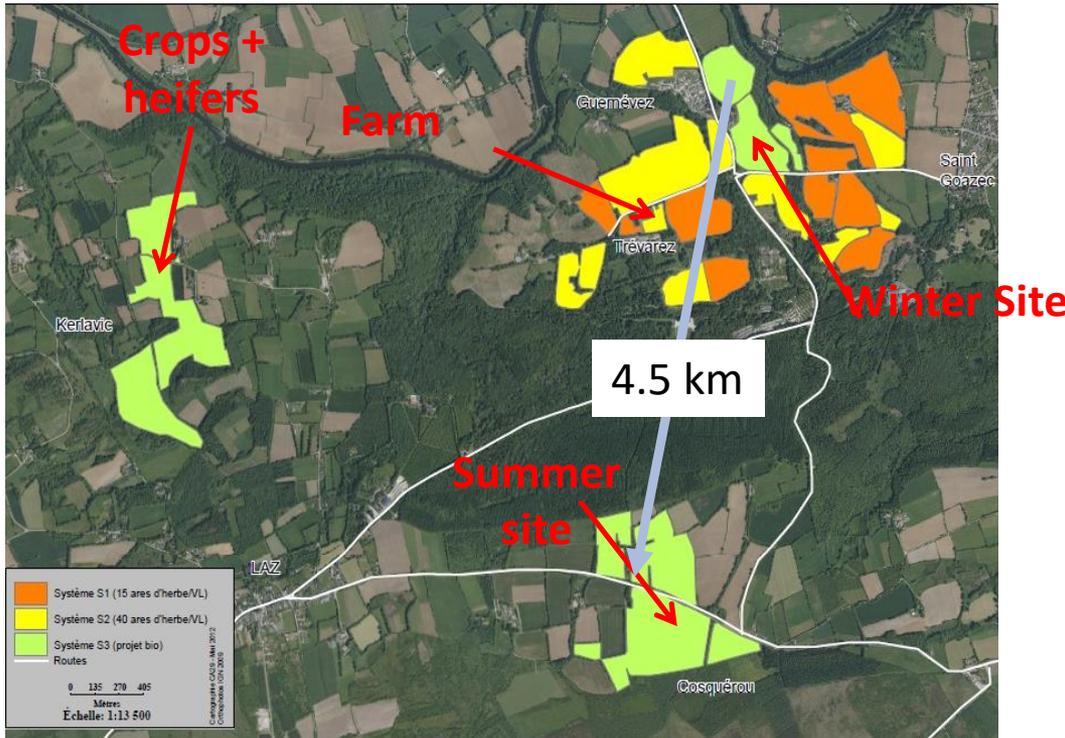
- 85 ha
- 55 Holstein cows
- Production: 5,200 kg cow<sup>-1</sup> yr<sup>-1</sup>
- Crossbreeding in progress
- 2 \* 3 months calving periods (spring and autumn)



Target: maximal feeding and protein self sufficiency (no purchase of concentrate)

- Maximal grass use, minimal concentrate use
- Minimal working time (no fetching of cows)

# The background: a fragmented land design for a grass based system



The robot trailer inside the winter shed



The tank trailer

# The solution: a mobile robot

The summer location  
(6 months per year)



# The robot on the summer site

Camera

Concentrate silo

Robot trailer

Tank trailer

Trévarez



3 directions drafting gate

Stabilized track

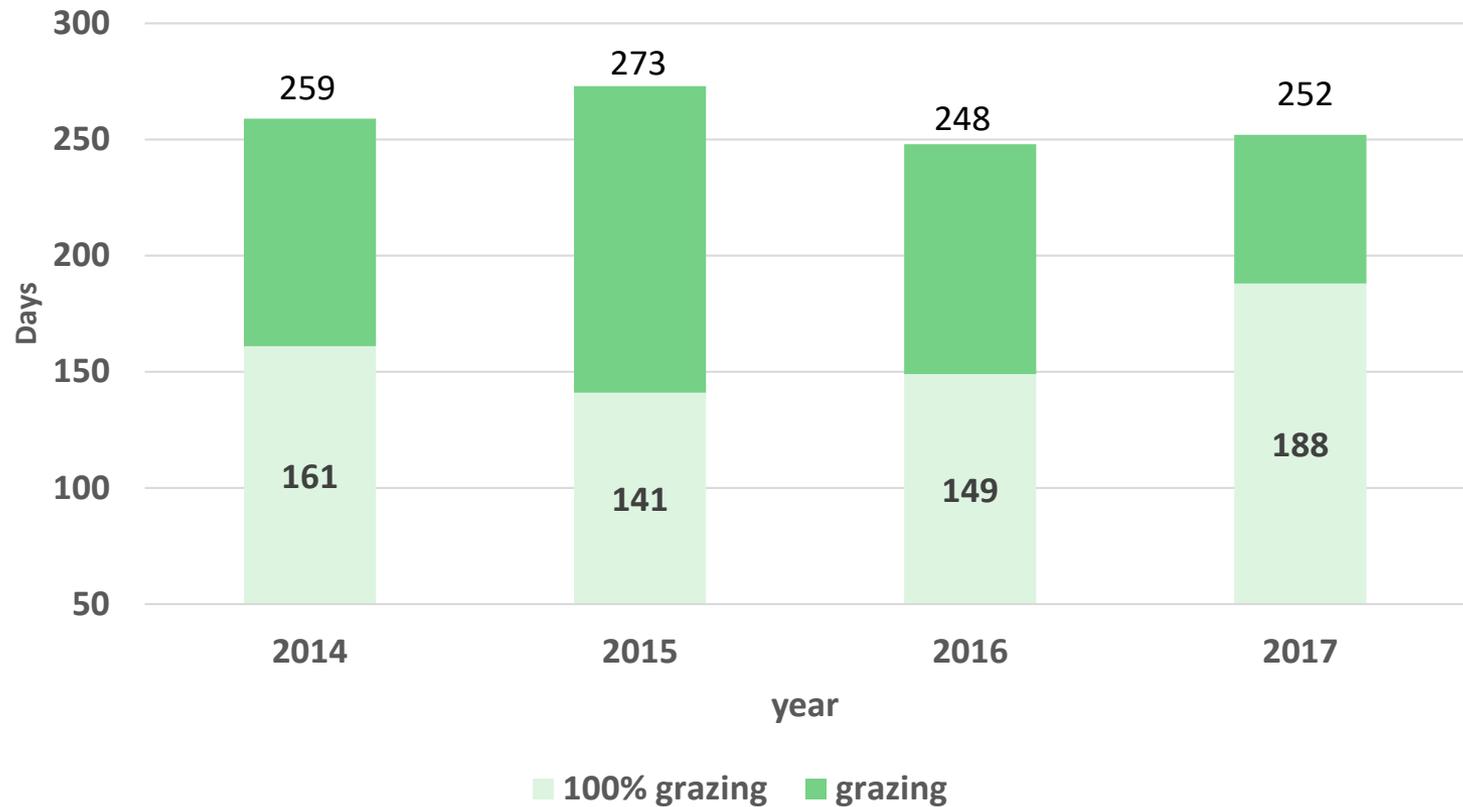
Waiting area/ slatted floor / pit

# The transfer management: not a problem

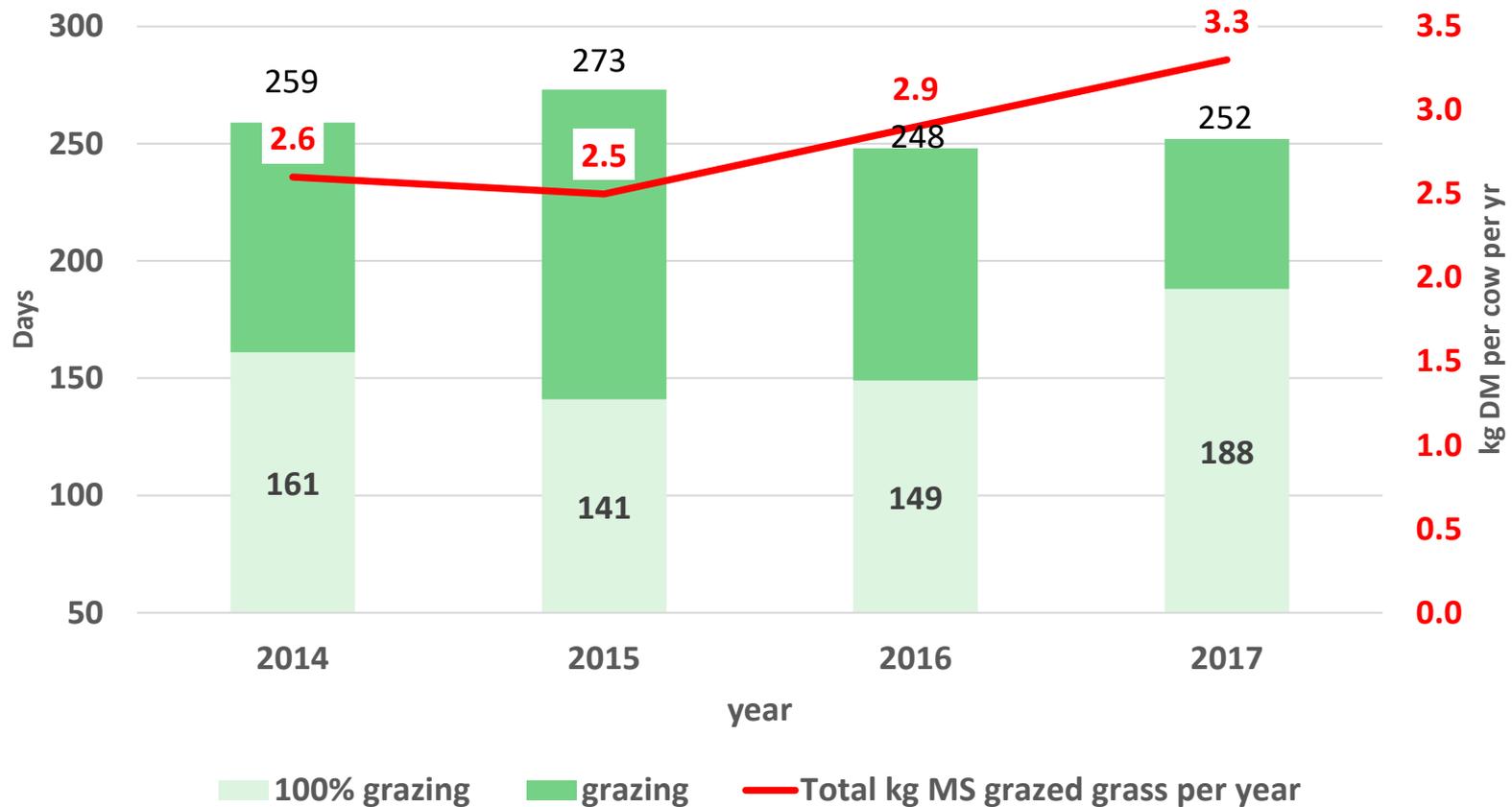
|  |                                  |
|--|----------------------------------|
| Number of transfers (*2) performed until now | 6                                |
| Distance winter site-summer site             | 4.5 km                           |
| Time required (human hours)                  | 13-17 h<br>(3 to 4 people)       |
| Transfer of                                  | Cows, tank, robot, drafting gate |
| Robot stopped                                | 3-4 h                            |

- Does not require presence of AMS retailer
- Duration of transfer = silage organisation





- 250 days grazing, 5 to 6 months 100% grazing



- 250 days grazing, 5 to 6 months 100% grazing
- Grazed grass intake increased up to 3.3 t DM per cow per yr

# Daily performances on the summer site

| YEAR                                    | 2014        | 2015        | 2016        | 2017        |
|---|-------------|-------------|-------------|-------------|
| <b>Grazing system</b>                   | <b>AB</b>   | <b>ABC</b>  | <b>ABC</b>  | <b>AB</b>   |
| # milking cows                          | 46          | 52          | 52          | 46          |
| Milk per box (kg per d )                | 867         | 911         | 914         | 786         |
| <b>Production per cow per day (kg)</b>  | <b>18.6</b> | <b>17.6</b> | <b>17.7</b> | <b>17.1</b> |
| Milking frequency (per cow per day)     | 1.8         | 1.8         | 1.7         | 1.5         |
| <b>Concentrate (kg per cow per day)</b> | <b>0.9</b>  | <b>0.7</b>  | <b>0.7</b>  | <b>0.7</b>  |

0.7 kg  
conc

18 kg  
milk

1.6  
milkings

# Conclusion: Mobility = Technically realistic

- Mobile robot robust, no technical issue until now
- Transfers = not a problem
- Grass use = 4 times higher than regional average for AMS farms
- Herd performances satisfactory for organic system
- Key factor for success: a well stabilized waiting area

# Summer site versus winter site

Feeding cost = -75 %

Working time =  
-2 h per day

What else?

Animal welfare  
Health  
Image  
Environment

# Thank you for your attention



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