



19th Symposium of the European Grassland Federation



Precision Farming New technologies for grazing management of ruminants



Valeria Giovanetti







Use of Information and Communication Technology (ICT) to monitor feeding behaviour in grazing ruminants

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Why BEHARUM project?

- Accurately monitoring of feeding behavior and nutrition of herbivores is still a challenge.
- Monitoring the feeding behavior in the pasture is important to take management decisions in grazing systems.
- Grazing, ruminating and resting are the main daily activities of ruminants and play a key role in regulating their **herbage intake**.

Daily herbage intake



Methods for monitoring feeding behaviour

1) Direct observation



2) Automatic recording

Acoustic system



IGER Behaviour Recorder



BEHARUM 1.0

Minimum impact on animal







850 g

40 g

Transmits reliable data from animal to a remote computer





Long recording sessions – easy battery recharge

Upgradable system

BEHARUM 1.0



It is a spring-like sensor

The tri-axial (x, y, z) **accelerometer sensor** (ADXL335) is inserted in a micro-electromechanical compact system (**MEMS**) with lots of on-board peripherals.



When deformed, it generates a voltage signal that is proportional to the acceleration it experiences. It is affected both by **static acceleration of gravity** as well as **dynamic acceleration** due to movement.

The central part of the system is a **microcontroller** (16F1825) that samples the row acceleration data at a frequency of **62.5 Hz** and encodes them into levels ranging from 0 to 255, then selects only three acceleration converted values per second and axis. The power supply of the system is guarantee by a Li-Polymer **battery**.

ZigBee wireless communication technology (IEEE 802.15.4) operates on 2.4 GHz bands, can cover distances up to 1500 meters.



Data Acquisition Control and Analysis Software

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		25	10:22:22	0	0	0	0	1	7	0	0	0	0	0	0	
		26	10:22:24	1	3	0	0	1	4	0	0	1	3	0	0	
		27	10:22:25	1	4	0	0	1	7	0	0	1	4	0	0	
		28	10:22:26	0	0	0	0	1	4	0	0	0	0	0	0	
		29	10:22:27	1	3	6	0	2	5	14	0	1	4	0	0	
		30	10:22:29	1	4	0	0	0	0	0	0	0	0	0	0	
		31	10.25.30	0	0	0	0	0	0	0	0	0	0	0	0	

Mean Variance Inverse Coefficient of Variation

X, Y, Z axis and the resultant



Italian ryegrass – Sulla – Alfalfa - Chicory

 We classified the video-recorded behavior of the animals into three simplified activities at 60 s intervals as:

Grazing, Ruminating, Resting

- 2. Datasets by combining the **three behaviours** and **number of bites** with the variables concerning accelerations
- 3. Multivariate statistical approach: Stepwise, Canonical, Discriminant analysis

Livestock Science 196 (2017) 42-48



Automatic classification system for grazing, ruminating and resting behaviour of dairy sheep using a tri-axial accelerometer



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Observed behaviour	Predicted behaviour						
	Grazing	Ruminating	Resting	Total			
Grazing	234	8	6	247			
Ruminatin	1	133	15	149			
Resting	9	9	261	279			
Total	244	149	282	675			
Sensitivity (%)	96	89	93				
Specificity (%)	97	97	95				
Precision (%)	95	89	94				
Accuracy (%)	96	95	94	93 ^a			
k	0.92	0.86	0.89	0.89 ^{\$}			

The total error in minutes assignment was around 7%

The sum of accelerazione in the X-axis represented a good proxy of number of bites (r2=0,65)

BEHARUM 2.0

Halter

(PIC18F87J50)

SD card



Server

Mother Board

- CPU Intel Atom quad core Z3736F, 1.83GHz
- Operating System Windows 10
- RAM 2Gb
- Micro SD up to 64Gb

Transceiver LoRa XTR-8LR100

Router 3G RUT500

Solar Charger Controller SC-LI11V

4 days, 8 animals. Video recording and direct observation.

- space mixed sward
- time mixed sward

berseem clover & italian ryegrass: 6 hours berseem clover + italian ryegrass: 3+3 hours

Short-term: micro-swards (Orr et al., 2005)

To calibrate the BEHARUM device for **bite/chew bite** number in Sarda dairy ewes



5x5 Latin square design: 5 forage specie, 2 replicates

Calibration of **BEHARUM** to measure feeding behaviour of grazing cattle raised on natural pasture





Decandia et al., 2017 Poster session - EGF Proceedings

Is **60 s** the best aggregation window to process acceleration data?

Correct classification rate (%)

Epoch setting	Sheep	Cattle
5 s	79	78
10 s	87	83
30 s	93	89
60 s	89	91
120 s	87	92
180 s	86	93
300 s	79	93

....on going

Is the under lower jaw (1) the best sensor position?



.....future purposes

To upgrade the device with other sensors (GPS, heart rate)

On farm long recording sessions with sheep and cattle

Thank you